

INNOVATE-IT



Task 4 – Fetch and Retrieve:

Goal: Program the robot to locate, pick up, and return an object to a designated area.

Rules:

The dog will start with its front feet behind the start line. The time will begin when the dog moves. The dog will locate the object. The dog will move to the object. The dog will pick up the object, then turn around and head back to the start line. The time stops when a foot crosses the start line on its way back.

Station Layout:

The object will be placed 5 ft from the start line.

